## Robust estimation on Controlled Branching Processes: minimum disparity approach

## M. González, C. Minuesa, I. del Puerto





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#### Controlled Branching Process

- Probability Model
- Main investigated topics

#### 2 Setting out the problem

3 Minimum disparity estimation

#### Simulated examples

- Example 1
- Example 2

#### 5 Concluding remarks and references

- Concluding remarks
- References

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#### Definition (Yanev (1975))

Let  $\{X_{ni} : n = 0, 1, ...; i = 1, 2, ...\}$  and  $\{\phi_n(k) : n, k = 0, 1, ...\}$  be two independent families of non negative integer valued random variables which are defined on the same probability space,  $(\Omega, \mathcal{A}, P)$ .

- (i)  $\{X_{ni} : n = 0, 1, \dots; i = 1, 2, \dots\}$  are i.i.d. random variables whose distribution is denoted by  $p = \{p_k\}_{k \ge 0}$ ,  $p_k = P[X_{01} = k]$ ,  $k \ge 0$ .
- (ii) For each n = 0, 1, ..., {φ<sub>n</sub>(k) : k = 0, 1, ...} are independent stochastic processes with equal one-dimensional probability distributions, i.e., for each n, p<sub>j</sub>(k) = P[φ<sub>n</sub>(k) = j], j, k ≥ 0.

The stochastic process  $\{Z_n\}_{n\geq 0}$  defined as:

$$Z_0 = N \ge 0, \quad Z_{n+1} = \sum_{i=1}^{\phi_n(Z_n)} X_{ni}, \quad n = 0, 1, \quad \left(\sum_{i=1}^0 0\right),$$

is known as Controlled Branching Process (CBP) with random control function.

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#### Examples of CBPs

- CBP with determinist control (Sebast'yanov and Zubkov (1974)).
- Standard branching process (Bienaymè-Galton-Watson).
- Branching process with immigration (Sriram (1994)).
- Branching process with immigration at state zero (Bruss and Slavtchova-Bojkova (1999)).
- Branching process with random migration (Yanev and Yanev (1996))
- Branching process with bounded emigration (del Puerto and Yanev (2008)).
- Branching process with adaptive control (Bercu (1999)).
- Branching process with continuous state space (Rahimov and Al-Sabah (2007)).

#### Main parameters of the model

- $p = \{p_k\}_{k \ge 0}$ : offspring distribution or reproduction law.
- $m = E[X_{01}]$ : offspring mean.
- $\sigma^2 = Var[X_{01}]$ : offspring variance.

#### • $\{p_j(k)\}_{k,j\geq 0}$ : control law.

- $\varepsilon(k) = E[\phi_0(k)], \quad k = 0, 1, \dots$ : control mean.
- $\sigma^2(k) = Var[\phi_0(k)], \quad k = 0, 1, \dots$ : control variance.



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### Main investigated topics

#### Properties

- {Z<sub>n</sub>}<sub>n≥0</sub> is an homogeneous Markov Chain with stationary transition probabilities.
- Duality Extinction-Explosion:  $P(Z_n \rightarrow 0) + P(Z_n \rightarrow \infty) = 1$ .

#### Main investigated topics

- Extinction Problem:
  - Sevastyanov and Zubkov (1974).
  - Zubkov (1974).
  - Yanev (1975).
  - González, Molina, and del Puerto (2002, 2005a).
- Asymptotic Behaviour. Growth rates:
  - Bagley (1986).
  - González, Molina, and del Puerto (2002, 2003, 2005a,b).

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### Main investigated topics

#### Main investigated topics: Statistical Inference

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### Assumption

The offspring distribution belongs to a parametric family

$$\mathcal{F}_{ heta} = \{ p( heta) : heta \in \Theta \}, \qquad \Theta \subseteq \mathbb{R}_{+}$$

that is,  $p = p(\theta_0)$ , with  $\theta_0 \in \Theta$ .

#### Aim

To obtain a robust estimator of  $\theta_0$  and, in consequence, of  $p(\theta_0)$ ,  $m(\theta_0)$  and  $\sigma^2(\theta_0)$ .

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#### Maximum likelihood estimation in a nonparametric context

Assuming that we can observe the random variables

$$\mathcal{Z}_n^* = \left\{ Z_l(k) = \sum_{i=1}^{\phi_l(Z_l)} I_{\{X_{li}=k\}} : k \ge 0; l = 0, \dots, n-1 \right\}$$

it is proved that the maximum likelihood estimator (MLE) of  $p_k$ ,  $k \ge 0$ , m, and  $\sigma^2$  are:

$$\hat{p}_{k} = \frac{\sum_{l=0}^{n-1} Z_{l}(k)}{\sum_{l=0}^{n-1} \phi_{l}(Z_{l})}, \quad \hat{m}_{n} = \frac{\sum_{l=0}^{n-1} Z_{l+1}}{\sum_{l=0}^{n-1} \phi_{l}(Z_{l})}, \quad \hat{\sigma}_{n}^{2} = \sum_{k=0}^{\infty} (k - \hat{m}_{n})^{2} \hat{p}_{k}.$$

• González, M., M.C., del Puerto, I. (2015). CSDA.

#### Maximum likelihood estimation in a parametric context

Assuming that  $p \in \mathcal{F}_{\Theta}$  and that we observe  $\mathcal{Z}_n^*$ , one can obtain the maximum likelihood estimator of  $\theta_0$  by maximizing the log-likelihood

$$\ell(\theta \mid \mathcal{Z}_n^*) = \sum_{l=0}^{n-1} \log\left(\frac{\phi_l^* !}{\prod_{k=0}^{\infty} Z_l(k) !}\right) + \sum_{l=0}^{n-1} \log(p_{\phi_l^*}(Z_l)) + \sum_{l=0}^{n-1} \sum_{k=0}^{\infty} Z_l(k) \log(p_k(\theta)).$$

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Thus,

$$\hat{\theta}_n = \arg \max_{\theta \in \Theta} \sum_{l=0}^{n-1} \sum_{k=0}^{\infty} Z_l(k) \log(p_k(\theta))$$

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Thus,

$$\hat{\theta}_n = \arg \max_{\theta \in \Theta} \sum_{l=0}^{n-1} \sum_{k=0}^{\infty} Z_l(k) \log(p_k(\theta)) = \arg \max_{\theta \in \Theta} \sum_{k=0}^{\infty} \hat{p}_{n,k} \log(p_k(\theta))$$
$$\widehat{p(\theta_0)}_{n,k} = p_k(\hat{\theta}_n), \quad \widehat{m(\theta_0)}_n = m(\hat{\theta}_n), \quad \widehat{\sigma(\theta_0)}_n^2 = \sigma(\hat{\theta}_n)^2.$$

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#### Simulated example

#### Behaviour of the MLEs against model perturbations

- Parametric family:  $\mathcal{F}_{\theta} = \{\mathcal{P}(5,\theta) : \theta \in (0,\infty)\},\$ where  $\mathcal{P}(5,\theta)$  denotes a Poisson distribution with parameter  $\theta$  truncated at 5.
- Mixture model for gross errors:  $p(\theta, \alpha, L) = (1 \alpha)p(\theta) + \alpha\delta_L$ , where  $p(\theta)$  is the probability mass function of  $\mathcal{P}(5, 1.2)$ ,  $\alpha = 0.1$  and L = 5.



#### Simulated example



#### Minimum Hellinger distance estimation

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## Minimum disparity estimation

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#### Disparity measure

Let  $\Gamma$  be the set of all probability mass functions defined on non-negative integers. A **disparity measure** between  $q \in \Gamma$  and  $p(\theta) \in \mathcal{F}_{\theta}$  is defined by:

$$\rho(q,\theta) = \sum_{k=0}^{\infty} G(\delta(q,\theta,k)) p_k(\theta),$$

with  $G(\cdot)$  a three times differentiable and strictly convex function on  $[-1,\infty)$  with G(0)=0 and

$$\delta(q, \theta, k) = \frac{q_k}{p_k(\theta)} - 1$$
 (Pearson residual).

#### Our aim:

To determine

$$\arg\min_{\theta\in\Theta}\rho(\boldsymbol{p},\theta).$$

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Robust estimation on CBP

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**Our aim**: the minimum disparity estimator (MDE) To determine

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ho( ilde{ heta}_{n}, heta).$$

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$$-\frac{\partial\rho}{\partial\theta}(\tilde{p}_n,\theta)=\sum_{k=0}^{\infty}p'_k(\theta)A(\delta(\tilde{p}_n,\theta,k))=0,$$

with

$$A(\delta) = (\delta + 1)G'(\delta) - G(\delta)$$
 (RAF).

	MDE	Notation		
Likelihood disparity	MLDE	$LD(\tilde{p}_n, \theta)$	$(\delta+1)\log(\delta+1)$	
Squared Hellinger distance	MHDE	$HD(\tilde{p}_n, \theta)$	$[(\delta+1)^{1/2}-1]^2$	$2[(\delta+1)^{1/2}-1]$
Negative exponential disparity	MNEDE	$NED(\tilde{p}_n, \theta)$	$\exp(-\delta) - 1$	$1-(2+\delta)\exp(-\delta)$

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#### Examples of disparity measures

Disparity measure	MDE	Notation	$G(\delta)$	$A(\delta)$
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#### Disparity functional

The disparity functional is a functional T<sup>ρ</sup>: Γ → Θ satisfying the condition that for every q ∈ Γ

$$\mathcal{T}^{
ho}(q) = rg\min_{ heta \in \Theta} 
ho(q, heta)$$

if  $T^{\rho}(q)$  exists.

• 
$$\tilde{\theta}_n^{\rho}(\tilde{p}_n) = T^{\rho}(\tilde{p}_n).$$

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• Problem: the existence of

 $\min_{\theta \in \Theta} \rho(q, \theta).$ 

• Assumptions:  $\rho(q, \cdot)$  is continuous in  $\Theta$  and  $\Theta$  is a compact set.

Theorem 1: Existence and uniqueness of a disparity functional

Under the conditions  $\rho(q, \theta)$  is continuous in  $\theta$ ,  $\Theta$  is a compact set and the identifiability of  $\mathcal{F}_{\theta}$ , the existence and uniqueness the functional  $\mathcal{T}^{\rho}$  are verified.

#### Theorem 2: Continuity of a disparity functional

Under the conditions of Theorem 1, if

$$\sup_{\theta\in\Theta} |\rho(q_n,\theta) - \rho(q,\theta)| \to 0,$$

as  $q_n \to q$  in  $\ell_1$  then,  $T^{
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as  $q_n \to q$  in  $\ell_1$  then,  $T^{\rho}(q_n) \to T^{\rho}(q)$ , that is, the continuity of the functional  $T^{\rho}$  holds.

### Minimum disparity estimation: sample $\mathcal{Z}_n^*$

#### Theorem 3: Consistency of the MDE

Suppose that  $T^{\rho}(p)$  is unique, where  $p = p(\theta_0)$  is the true reproduction law. Then, under conditions which guarantee  $\tilde{p}_{n,k}$  is a consistent estimator of  $p_k$  and the assumptions of Theorems 1 and 2,

$$\widetilde{ heta}^
ho_n(\widetilde{p}_n)=T^
ho(\widetilde{p}_n) o T^
ho(p)= heta_0$$
 a.s.

In particular, for  $\hat{p}_n$ ,

$$\hat{\theta}_n^{\rho}(\hat{p}_n) \to \theta_0$$
 a.s. on  $\{Z_n \to \infty\}$ .



### Minimum disparity estimation: sample $Z_n^*$

#### Theorem 4: Asymptotic normality of the MDE

Let  $p = p(\theta_0)$  be the true reproduction law. Under certain assumptions,

$$\left(\sum_{l=0}^{n-1}\phi_l(Z_l)\right)^{1/2}(\tilde{\theta}_n^{\rho}(\hat{p}_n)-\theta_0)\to N\left(0,I(\theta_0)^{-1}\right),$$

with respect to the distribution  $P[\cdot|Z_n \to \infty]$ , being

$$I(\theta_0) = \sum_{k=0}^{\infty} \left( \frac{p'_k(\theta_0)}{p_k(\theta_0)} \right)^2 p_k(\theta_0).$$



• Sample:

$$\overline{\mathcal{Z}}_n = \{Z_0, \ldots, Z_n, \phi_0(Z_0), \ldots, \phi_{n-1}(Z_{n-1})\}$$

• **Problem**: to determine a nonparametric estimator of  $p_k$ ,  $k \ge 0$ , based on  $\overline{\mathbb{Z}}_n$ .

$$\ell(p|\overline{Z}_n) = \sum_{l=0}^{n-1} \log \left( P[\phi(z_l) = \phi_l^*] \right) + \sum_{l=0}^{n-1} \log \left( \sum_{i_1 + \dots + i_{\phi_l^*} = z_{l+1}} p_{i_1} \dots p_{i_{\phi_l^*}} \right)$$

Methodology: Expectation-Maximization algorithm.

- Nonparametric estimator of p based on  $\overline{Z}_n$ :  $\widehat{p}_{n,k}^{EM}$ 
  - González, M., M.C., del Puerto, I. (2015). CSDA.
- **Consistency**:  $\hat{\theta}_n^{\rho}(\hat{p}_n^{EM})$  is strongly consistent as  $\hat{p}_{n,k}^{EM}$  is for each  $k \ge 0$ .



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$$\overline{\mathcal{Z}}_n = \{Z_0, \ldots, Z_n, \phi_0(Z_0), \ldots, \phi_{n-1}(Z_{n-1})\}$$

• **Problem**: to determine a nonparametric estimator of  $p_k$ ,  $k \ge 0$ , based on  $\overline{\mathbb{Z}}_n$ .

$$\ell(p|\overline{Z}_n) = \sum_{l=0}^{n-1} \log \left( P[\phi(z_l) = \phi_l^*] \right) + \sum_{l=0}^{n-1} \log \left( \sum_{i_1 + \dots + i_{\phi_l^*} = z_{l+1}} p_{i_1} \dots p_{i_{\phi_l^*}} \right)$$

- Methodology: Expectation-Maximization algorithm.
- Nonparametric estimator of *p* based on  $\overline{Z}_n$ :  $\hat{p}_{n,k}^{EM}$ .
  - González, M., M.C., del Puerto, I. (2015). CSDA.
- **Consistency**:  $\hat{\theta}_n^{\rho}(\hat{p}_n^{EM})$  is strongly consistent as  $\hat{p}_{n,k}^{EM}$  is for each  $k \ge 0$ .

### Minimum disparity estimation: sample $Z_n$

• Sample:

$$\mathcal{Z}_n = \{Z_0, \ldots, Z_n\}$$

• **Problem**: to determine the MLE of  $p_k$ ,  $k \ge 0$ , based on  $\mathcal{Z}_n$ .

$$\ell(\boldsymbol{p}|\mathcal{Z}_n) = \sum_{l=0}^{n-1} \log \left( \delta_0(z_{l+1}) P[\phi(z_l) = 0] + \sum_{j=1}^{\infty} P[\phi(z_l) = j] \sum_{i_1 + \ldots + i_j = z_{l+1}} \prod_{k=1}^j p_{i_k} \right)$$

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#### • Mixture model for gross error:

$$p(\theta, \alpha, L) = (1 - \alpha)p(\theta) + \alpha \delta_L.$$

•  $\alpha$ -influence curves of  $T^{\rho}$ :

$$L \in \mathbb{N}_0 \mapsto \alpha^{-1}(T^{\rho}(p(\theta, \alpha, L)) - \theta), \quad \alpha \in (0, 1).$$

#### Theorem 5: Robustness of a disparity functional

Under conditions of Theorems 1 and 2, for every  $\alpha \in (0, 1)$ , every  $\theta \in \Theta$  and if  $T^{\rho}(p(\theta, \alpha, L))$  is unique for all L we have the functional  $T^{\rho}$  is robust at  $p(\theta)$  against  $100\alpha\%$  contamination by gross errors at arbitrary integer L.

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• Asymptotic breakdown point of a disparity functional  $T^{\rho}$  at  $q \in \Gamma$ :

$$lpha^*(\mathcal{T}^
ho, oldsymbol{q}) = \inf \left\{ lpha \in (0,1) : oldsymbol{b}(lpha; \mathcal{T}^
ho, oldsymbol{q}) = \infty 
ight\},$$

with

$$b(\alpha; T^{\rho}, q) = \sup \{ |T^{\rho}((1-\alpha)q + \alpha \overline{q}) - T^{\rho}(q)| : \overline{q} \in \Gamma \}.$$

#### Theorem 6: Asymptotic breakdown point

(i) Under certain conditions on the function *G* and the contaminant distributions,

$$\alpha^*(T^{\rho},p)\geq \frac{1}{2}.$$

(ii) Under conditions of Theorems 1 and 2, if  $\hat{\varrho} = \max_{t \in \Theta} \sum_{k=0}^{\infty} (p_k(\theta_0) p_k(t))^{1/2}$ and  $\varrho^* = \lim_{M \to \infty} \sup_{|t| > M} \sum_{k=0}^{\infty} (p_k(\theta_0) p_k(t))^{1/2}$ , then

$$\alpha^*(T^{\rho}, p) \ge \frac{(\hat{\varrho} - \varrho^*)^2}{[1 + (\hat{\varrho} - \varrho^*)^2]}.$$

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### Simulated example 1: sample $\mathcal{Z}_n^*$



### Simulated example 1: samples $\mathcal{Z}_n^*$ , $\overline{\mathcal{Z}}_n$ , $\mathcal{Z}_n$



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Carmen Minuesa (University of Extremadura)

### Simulated example 2: uncontaminated model

We have simulated the first 50 generations of 100 CBPs verifying:

- They start with  $Z_0 = 1$  individual.
- The distribution of the variables  $X_{ij} \sim \mathcal{P}(\theta_0)$ , with  $\theta_0 = 4$  for i = 0, 1, ..., j = 1, ...
- $\phi_n(k) \sim \mathcal{P}(k\lambda)$ , with  $\lambda = 0.3$ ,  $n \in \mathbb{N}$ ,  $k \ge 0$ .

- $\frac{1}{100}\sum_{i=1}^{100}\tilde{\theta}_i^{LD}$  (black line).
- $\frac{1}{100}\sum_{i=1}^{100}\tilde{\theta}_i^{HD}$  (blue line).
- $\frac{1}{100}\sum_{i=1}^{100}\tilde{\theta}_i^{NED}$  (green line).



### Simulated example 2: under mixture models for gross errors

We have simulated 100 CBPs following the previous model and with offspring distribution contaminated according to the mixture model for gross error:

- $L = 0, \ldots, 25$ .
- $\alpha = 0.05, 0.1, 0.15, 0.2, 0.25, 0.3, 0.35, 0.4, 0.45, 0.5.$



#### Simulated example 2: under mixture models for gross errors



- For a CBP with offspring distribution belonging to a parametric family  $\mathcal{F}_{\theta}$ , we have deduced the **minimum disparity estimator of**  $\theta_0$ ,  $p(\theta_0)$ ,  $m(\theta_0)$  and  $\sigma^2(\theta_0)$  based on the **whole family tree** and we have established the **consistency** and **asymptotic normality** of the minimum disparity estimator of  $\theta_0$ .
- For a CBP with offspring distribution belonging to a parametric family  $\mathcal{F}_{\theta}$ , we have also determined the **minimum disparity estimators** of the main parameters of the model considering only the **total number of individuals** and progenitors in each generation or only the population sizes.
- We have studied **robustness against model perturbations and resistance to outliers of the minimum disparity estimator** for a certain family of disparities. These properties show that the related minimum disparity estimators are better choices than maximum likelihood estimators.
- We have **implemented** the **minimum disparity estimation** using statistical software and programming environment **R**.

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## Concluding remarks

- For a CBP with offspring distribution belonging to a parametric family  $\mathcal{F}_{\theta}$ , we have deduced the **minimum disparity estimator of**  $\theta_0$ ,  $p(\theta_0)$ ,  $m(\theta_0)$  and  $\sigma^2(\theta_0)$  based on the whole family tree and we have established the **consistency** and **asymptotic normality** of the minimum disparity estimator of  $\theta_0$ .
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